

3 Axis Cartesian Robot Training System

Model: FA-RA801

Design subject to change based on robot selection size

Overview

A 3 Axis Cartesian Robot Arm is a type of industrial robot designed to move in three linear directions: X, Y, and Z axes. It operates using a set of motors and linear actuators to achieve precise and repeatable movements in a Cartesian coordinate system. This type of robot is often used in applications requiring accurate positioning and handling, such as in pick-and-place tasks, assembly, and automated testing. Its straightforward design makes it ideal for tasks requiring linear motion and can be integrated into various manufacturing and laboratory environments.

Learning Outcome

- 1 Function and characteristic of cartesian robot arm system
- 2 Design a control architecture integrating PLC, drives, and sensors.
- 3 Program robot kinematics (forward/inverse) for precise motion planning.
- 4 Design HMI screens for control, status, and alarm
- 5 Fault findings robot arm electrical control system

Technical Specification

Robot Arm

- 1 unit X-axis linear drive 300mm
- 1 unit Y-axis linear drive 300mm
- 1 unit Z-axis linear drive 100mm
- Payload 3kg
- Maximum speed 600m/s
- Repeatability 0.02mm
- 1 unit end effector Gripper

PLC Control Panel

- 1 unit assembly aluminum profile working table 900x900mm .
- 1 set HMI 7" + PLC 40 I/O
- 1 set license programming software
- Ethernet communication protocol
- 1 set tower lamp status indication
- 1 set operation push button (Start, Stop, Estop, Reset)
- 1 lot vacuum Pick and Place system
- 1 lot photo sensor
- 1 lot of work piece
- 1 lot of cavity storage tray

Training & Documentation

2 days + Training Manual

Warranty

12 months against manufacturing defects only

Delivery

8-10 weeks



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